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ON TIME-OPTIMAL CONTROL PROBLEM ASSOCIATED WITH PARABOLIC EQUATION

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Abstract

The boundary control problem for heat equation in a right rectangle domain is considered. The control parameter is equal to the temperature on some part of the border of the considered domain. The estimate of a minimal time for achieving the given average temperature over some subdomain is found.

Keywords: *Minimal time, integral equation, boundary control, initial-boundary problem, admissible control.*

Mathematics Subject Classification (2010): 35K05, 35K15.

Introduction

Consider the following mathematical model of the heat conduction process along the domain $\Omega = \{(x, y) \in R^2 : 0 < x < a, 0 < y < b\}$:

$$u_t = u_{xx} + u_{yy}, \quad (x, y) \in \Omega \quad t > 0, \quad (1)$$

with boundary conditions

$$u|_{x=0} = \varphi(y)\mu(t), \quad u|_{x=a} = 0, \quad 0 < x < a, \quad (2)$$

$$u|_{y=0} = 0, \quad u|_{y=b} = 0, \quad 0 < y < b, \quad t > 0, \quad (3)$$

and initial condition

$$u(x, y, 0) = 0, \quad 0 \leq x \leq a, \quad 0 \leq y \leq b. \quad (4)$$

Let $M > 0$ be some given constant. We say that the function $\mu(t)$ is an *admissible control* if this function is differentiable on the half-line $t \geq 0$ and satisfies the following constraints

$$\mu(0) = 0, \quad |\mu(t)| \leq M, \quad t > 0. \quad (5)$$

Assume that the function $\varphi(y) \in W_2^2[0, b]$ is smooth and satisfies conditions

$$\varphi(0) = \varphi(b) = 0, \quad \varphi_m \geq 0, \quad 0 \leq y \leq b, \quad (6)$$

where

$$\varphi_m = \frac{2}{b} \int_0^b \varphi(y) \sin \frac{m\pi y}{b} dy. \quad (7)$$

Set of functions which satisfies conditions (6) is not empty. For example:

$$\varphi(y) = y(b-y) = \sum_{m=1}^{\infty} \varphi_m \sin \frac{m\pi y}{b}, \quad 0 \leq y \leq b.$$

In the present work we consider the following problem.

Problem A. Given constants $\alpha, \beta \geq 1$ and $\theta > 0$ Problem A consists in looking for the minimal value of $T > 0$ so that for $t > 0$ the solution $u(x, y, t)$ of the initial-boundary value problem (1)-(4) with some admissible control $\mu(t)$ exists and for all $t \geq T$ satisfies the equation

$$\int_0^{b/\alpha} \int_0^{a/\beta} u(x, y, t) dx dy = \theta, \quad t \geq T. \quad (8)$$

We recall that the time-optimal control problem for partial differential equations of parabolic type was first concerned in [6] and [9]. More recent results concerned with this problem were established in [1]-[5], [7], [8], [15], [16]. Detailed information on the problems of optimal control for distributed parameter systems is given in the monographs [10] and [14].

General numerical optimization and optimal boundary control have been studied in a great number of publications such as [13].

To formulate the main result we use some data related to the conditions of the boundary-initial problem (1)-(4).

Set

$$\rho_{nm} = \frac{8b\varphi_m}{am\pi} \sin^2 \frac{n\pi}{2\beta} \sin^2 \frac{m\pi}{2\alpha}, \quad n, m = 1, 2, 3, \dots \quad (9)$$

Theorem 0.1. Let

$$0 < \theta < \frac{\rho_{11} M a^2 b^2}{\pi^2 (a^2 + b^2)}.$$

Set

$$T_0 = -\frac{a^2 b^2}{\pi^2 (a^2 + b^2)} \ln \left(1 - \frac{\theta \pi^2 (a^2 + b^2)}{\rho_{11} M a^2 b^2} \right).$$

Then a solution T_{min} of the Problem A exists and the estimate $T_{min} \leq T_0$ is valid.

1 The main integral equation

Let B be the Banach space and $T > 0$. Denote by $C([0, T] \rightarrow B)$ the Banach space of all continuous maps $u : [0, T] \rightarrow B$ with the norm

$$\|u\| = \max_{0 \leq t \leq T} \|u(t)\|.$$

By symbol $\widetilde{W}_2^1(\Omega)$ we denote the subspace of the Sobolev space $W_2^1(\Omega)$ formed by functions whose trace is equal to $\partial\Omega$ zero. Note that since $\widetilde{W}_2^1(\Omega)$ is closed, the sum of a series of functions from $\widetilde{W}_2^1(\Omega)$ converging in metric $W_2^1(\Omega)$ also belongs to $\widetilde{W}_2^1(\Omega)$.

Definition 1.1. By the solution of problem (1) - (4) we mean function $u(x, y, t)$, represented in the form

$$u(x, y, t) = \frac{a-x}{a} \varphi(y) \mu(t) - v(x, y, t),$$

where the function $v(x, y, t)$ is a generalized solution from $C([0, T] \rightarrow \widetilde{W}_2^1(\Omega))$ of the problem

$$v_t(x, y, t) - \Delta v(x, y, t) = -\frac{a-x}{a} \varphi''(y) \mu(t) + \frac{a-x}{a} \varphi(y) \mu'(t),$$

with boundary conditions

$$v(x, y, t) |_{\partial\Omega} = 0,$$

and initial condition

$$v(x, y, 0) = 0, \quad 0 \leq x \leq a, \quad 0 \leq y \leq b.$$

Consequently,

$$v(x, y, t) = \int_0^t \sum_{n,m=1}^{\infty} e^{-\lambda_{nm}(t-s)} \frac{\varphi_m}{n} \sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} \left(\frac{2\pi m^2}{b^2} \mu(s) + \frac{2}{\pi} \mu'(s) \right) ds,$$

where $\lambda_{nm} = (n\pi/a)^2 + (m\pi/b)^2$, $n, m = 1, 2, \dots$ (see, e.g. [17], [18]).

Note that the class $C([0, T] \rightarrow \widetilde{W}_2^1(\Omega))$ is a subset of the class $W_2^1(\Omega)$ considered in the monograph [11] in order to define a problem with homogeneous boundary conditions. Thus, the generalized solution introduced above is also a generalized solution in the sense of monograph [11]. However, unlike a solution from the class $W_2^1(\Omega)$, which is guaranteed to have a trace of almost all $t \in [0, T]$, a solution from the class $C([0, T] \rightarrow \widetilde{W}_2^1(\Omega))$ continuously depends of $t \in [0, T]$ in the metric $L_2(\Omega)$.

Proposition 1.1. Let $\mu(t)$ be a smooth function on the half-line $t \geq 0$ and $\varphi \in W_2^2[0, b]$. Then the function

$$u(x, y, t) = \int_0^t \mu(s) \sum_{n,m=1}^{\infty} \frac{2\pi n \varphi_m}{a^2} e^{-\lambda_{nm}(t-s)} \sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} ds, \quad (10)$$

is the solution of the initial-boundary value problem (1)-(4).

Proof. A similar proof is given in the case [12]. We rewrite the solution to the problem in the form

$$u(x, y, t) = \frac{a-x}{a} \varphi(y) \mu(t) - \int_0^t \sum_{n,m=1}^{\infty} e^{-\lambda_{nm}(t-s)} \frac{\varphi_m}{n} \sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} \left(\frac{2\pi m^2}{b^2} \mu(s) + \frac{2}{\pi} \mu'(s) \right) ds.$$

We show that function $v(x, y, t)$ belongs to class $C([0, T] \rightarrow \widetilde{W}_2^1(\Omega))$. For this, it is enough to prove that the gradient of this function, taken in $(x, y) \in \Omega$, continuously depends on $t \in [0, T]$ in the norm of the space $L_2(\Omega)$. According to Parseval's equality, the norm of this gradient is

$$\|\nabla v\|_{L_2(\Omega)}^2 = \sum_{n,m=1}^{\infty} \frac{|\varphi_m|^2}{n^2} \lambda_{nm} b_{nm}^2(t)$$

where

$$b_{nm}(t) = \int_0^t e^{-\lambda_{nm}(t-s)} \left(\frac{2\pi m^2}{b^2} \mu(s) + \frac{2}{\pi} \mu'(s) \right) ds.$$

From the Cauchy-Bunyakovsky inequality, we obtain the following estimate

$$b_{nm}(t) \leq \frac{C_1}{\sqrt{\lambda_{nm}}} + C_2 \frac{m^2}{\lambda_{nm}} \leq C_3 \frac{m}{\sqrt{\lambda_{nm}}}, \quad t \geq 0.$$

From (6) and (7), we write

$$\begin{aligned} \varphi_m &= \frac{2}{b} \int_0^b \varphi(y) \sin \frac{m\pi y}{b} dy = -\frac{2}{b} \varphi(y) \frac{b}{m\pi} \cos \frac{m\pi y}{b} \Big|_{y=0}^{y=b} + \\ &+ \frac{2}{m\pi} \int_0^b \varphi'(y) \cos \frac{m\pi y}{b} dy = \frac{2}{m\pi} \int_0^b \varphi'(y) \cos \frac{m\pi y}{b} dy = \frac{b}{m\pi} \varphi'_m. \end{aligned} \quad (11)$$

Consequently,

$$\|\nabla v\|_{L_2(\Omega)}^2 \leq C_3 \sum_{n,m=1}^{\infty} \frac{m^2 |\varphi_m|^2}{n^2} \leq C_3 \frac{\pi^2}{6} \frac{b^2}{\pi^2} \sum_{m=1}^{\infty} m^2 \frac{|\varphi'_m|^2}{m^2} = C \|\varphi'\|_{L_2[0,b]}^2.$$

□

It is easy to see that with the equality (10) we can write the condition (8) of problem as the following

$$\begin{aligned} \theta &= \int_0^{b/\alpha} \int_0^{a/\beta} u(x, y, t) dx dy = \\ &= \int_0^t \mu(s) ds \int_0^{b/\alpha} \int_0^{a/\beta} \sum_{n,m=1}^{\infty} \frac{2\pi n}{a^2} \varphi_m e^{-\lambda_{nm}(t-s)} \sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} dx dy = \\ &= \int_0^t \mu(s) \sum_{n,m=1}^{\infty} \frac{8b \varphi_m}{a m \pi} e^{-\lambda_{nm}(t-s)} \sin^2 \frac{n\pi}{2\beta} \sin^2 \frac{m\pi}{2\alpha} ds. \end{aligned} \quad (12)$$

Set

$$B(t) = \sum_{n,m=1}^{\infty} \rho_{nm} e^{-\lambda_{nm}t}, \tag{13}$$

where ρ_{nm} defined by (9).

Then we get main integral equation

$$\int_0^t B(t-s)\mu(s)ds = \theta, \quad t > 0. \tag{14}$$

Proposition 1.2. For $B(t)$ defined by (13) the following estimate

$$0 < B(t) \leq \frac{C}{\sqrt{t}}, \quad 0 < t \leq 1, \tag{15}$$

is valid.

Proof. From (9) and (11), we may write

$$0 < \rho_{nm} \leq \frac{C_0 \varphi'_m}{m^2},$$

Hence, using the definition (13) we get

$$0 < B(t) \leq C_0 \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \frac{\varphi'_m}{m^2} e^{-\lambda_{nm}t} = C_0 \sum_{m=1}^{\infty} \frac{\varphi'_m}{m^2} e^{-\frac{\pi^2}{b^2}m^2t} \sum_{n=1}^{\infty} e^{-\frac{\pi^2}{a^2}n^2t}. \tag{16}$$

Set

$$K(t) = \sum_{m=1}^{\infty} \frac{\varphi'_m}{m^2} e^{-\frac{\pi^2}{b^2}m^2t}, \quad t > 0.$$

This function for any $T > 0$ and $0 \leq t \leq T$ satisfies inequalities

$$0 < K(T) \leq K(t) \leq K(0). \tag{17}$$

For any $p > 0$ consider the following relations:

$$\sum_{n=1}^{\infty} e^{-pn^2} = \sum_{n=1}^{\infty} \int_n^{n+1} e^{-p[s]^2} ds = \int_1^{\infty} e^{-p[s]^2} ds = \int_1^{\infty} e^{-ps^2} e^{p(s^2-[s]^2)} ds,$$

where $[s]$ is integer part of s .

Note that $e^{p(s^2-[s]^2)} = e^{p(s-[s])(s+[s])} \leq e^{2ps}$. Then we obtain

$$\int_1^{\infty} e^{-ps^2} e^{p(s^2-[s]^2)} ds \leq \int_1^{\infty} e^{-ps^2+2ps} ds = e^p \int_1^{\infty} e^{-p(s-1)^2} ds.$$

Hence, for $0 < p \leq \text{const}$ we get

$$\sum_{n=1}^{\infty} e^{-pn^2} \leq \int_1^{\infty} e^{-ps^2} e^{p(s^2-[s]^2)} ds \leq e^p \int_0^{\infty} e^{-ps^2} ds \leq \frac{C}{\sqrt{p}}. \tag{18}$$

Put $p = \frac{\pi^2 t}{a^2}$. Then required estimate (15) follows from (16)-(18).

□

2 Estimate of Minimal Time

We consider the following integral equation

$$\int_0^t B(t-s)\mu(s)ds = \theta, \quad t \geq T, \quad (19)$$

where

$$B(t) = \sum_{n,m=1}^{\infty} \rho_{nm} e^{-\lambda_{nm}t}. \quad (20)$$

Proposition 2.1. *For the function defined by equality (20) the following estimate*

$$B(t) \geq \rho_{11} e^{-[(\pi/a)^2 + (\pi/b)^2]t}, \quad (21)$$

is valid.

Proof. The proof comes from functional series defined by (20) is non-negative. \square

We introduce a specific heating as

$$Q(t) = \int_0^t B(t-s)ds = \int_0^t B(s)ds = \sum_{n,m=1}^{\infty} \frac{\rho_{nm}}{\lambda_{nm}} \left(1 - e^{-\lambda_{nm}t}\right). \quad (22)$$

The physical meaning of this function is evident: $Q(t)$ equals the average temperature of Ω in case where the heater is acting unit load (see, e.g. [1], [2]).

It is clear that $Q(0) = 0$ and $Q'(t) = B(t) \geq 0$.

Set

$$Q^* = \lim_{t \rightarrow \infty} Q(t) = \int_0^{\infty} B(s)ds. \quad (23)$$

Obviously, the average temperature of Ω in the case where the heater is acting with unit load cannot exceed Q^* .

Proposition 2.2. *Let*

$$0 < \theta < MQ^*. \quad (24)$$

Then there exist $T > 0$ and a real-valued measurable function $\mu(t)$ so that $|\mu(t)| \leq M$ and the following equality

$$\int_0^T B(T-s)\mu(s)ds = \theta \quad (25)$$

is valid.

Proof. This follows from the properties of the function Q . Indeed, if we set $\mu(t) = M$ then

$$\int_0^t B(t-s)\mu(s)ds = M \int_0^t B(t-s)ds = MQ(t),$$

and because of (25) there exists $T > 0$ so that $MQ(T) = \theta$. □

Remark 2.1. *It is clear that the value T , which was found in Proposition 2.2, gives a solution to the problem. Namely, T is the root of the equation*

$$Q(T) = \frac{\theta}{M}. \tag{26}$$

However, the main idea of the present work is to establish an acceptable estimate for the value of the minimal time T (see, e.g. [3]).

Proposition 2.3. *Let*

$$0 < \theta < \frac{\rho_{11} M a^2 b^2}{\pi^2(a^2 + b^2)}. \tag{27}$$

Then there exists $T > 0$ so that

$$T < -\frac{a^2 b^2}{\pi^2(a^2 + b^2)} \ln\left(1 - \frac{\theta \pi^2 (a^2 + b^2)}{\rho_{11} M a^2 b^2}\right) \tag{28}$$

and the equality (26) is fulfilled.

Proof. For obtaining the required estimate we use Proposition 2.1. We may write

$$\begin{aligned} Q(t) &= \int_0^t B(s)ds \geq \rho_{11} \int_0^t e^{-[(\pi/a)^2 + (\pi/b)^2]s} ds = \\ &= \frac{\rho_{11} a^2 b^2}{\pi^2(a^2 + b^2)} \left(1 - e^{-[(\pi/a)^2 + (\pi/b)^2]t}\right). \end{aligned} \tag{29}$$

Consider the following equation for the defining of T_0 :

$$\frac{\rho_{11} a^2 b^2}{\pi^2(a^2 + b^2)} \left(1 - e^{-[(\pi/a)^2 + (\pi/b)^2]T_0}\right) = \frac{\theta}{M}. \tag{30}$$

Then

$$T_0 = -\frac{a^2 b^2}{\pi^2(a^2 + b^2)} \ln\left(1 - \frac{\theta \pi^2 (a^2 + b^2)}{\rho_{11} M a^2 b^2}\right).$$

In accordance with (29) and (30) we may write

$$0 < \frac{\theta}{M} \leq Q(T_0).$$

Then obviously there exists T , $0 < T < T_0$, which is a solution to the equation (26). □

Proposition 2.4. *Let $T > 0$ satisfies the equality (26) and condition (27).*

Then there exist $T_1 > T$ and a measurable real-valued function $\mu(t)$ so that $|\mu(t)| \leq M$ and the following equality

$$\int_0^{b/\alpha} \int_0^{a/\beta} u(x, y, t) dx dy = \theta, \quad T \leq t \leq T_1,$$

is valid.

Proof. According to the following

$$\int_0^t B(t-s)\mu(s)ds = \theta, \quad (31)$$

it is enough to prove that there exists solution of the equation

$$\int_0^t B(t-s)\mu(s)ds = f(t), \quad 0 \leq t \leq T_1, \quad (32)$$

where

$$f(t) = \begin{cases} MQ(t), & \text{if } 0 \leq t \leq T, \\ \theta, & \text{if } T < t \leq T_1. \end{cases} \quad (33)$$

The solution (33) is piecewise smooth and, according to equality (26), is continuous.

Set

$$\mu(t) = \begin{cases} M, & \text{if } 0 \leq t \leq T, \\ \mu_1(t), & \text{if } T < t \leq T_1, \end{cases} \quad (34)$$

where $\mu_1(t)$ is the solution of the following integral equation

$$\int_0^T B(t-s)Mds + \int_T^t B(t-s)\mu_1(s)ds = \theta, \quad T \leq t \leq T_1. \quad (35)$$

After differentiating this equation we get

$$B(0)\mu_1(t) + \int_T^t B'(t-s)\mu_1(s)ds = M[B(t-T) - B(t)]. \quad (36)$$

According to (20) $B(0)$ positive and $B(t)$ function is convergence function on given interval. Hence, equation (36) has a unique solution $\mu_1(t)$ for all $t \geq T$, which is continuous function on the half line $t \geq T$. Besides,

$$\mu_1(T) = M \left(1 - \frac{B(T)}{B(0)} \right) < M,$$

and there exists $T_1 > T$ so that

$$|\mu_1(t)| \leq M, \quad T \leq t \leq T_1.$$

It is clear that this function is the unique solution of the equation (35). Hence, the function (34) is piecewise continuous and satisfies equation (32). Consequently, this function $\mu(t)$, which has a jump at the point $t = T$, is the required solution. \square

The proof of Theorem 0.1 follows now easily from Proposition 2.3 and Proposition 2.4.

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